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NYK autonomous ship project: Assisting crew

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Contribution of Autonomous Ship for Deep Sea





Case 1) NYK conducted world's first trial of MASS in accordance with IMO Interim Guidelines for MASS trials (Sep 2019)



- IRIS Leader, PCTC (NYK operation)
- Objective: onboard trial of automatic navigation system
- Trial schedule
 - Trial #1 ... 14th 16th Sep (Yonagunijima Ashizuri)
 - Trial #2 ... 19th 20th Sep (Nagoya Yokohama)
- Automatic navigation system
 - Information collection around ship from navigational devices
 - Calculation of collision risks
 - Automatic determination of optimal routes and speeds
 - Automatic navigation





Radar echo was used as the main sensor for situational awareness



PANAMA MARITIME AUTHORITY

Technical Office – Segumar Tokyo Samon Building1F, 2-21-7, Higashi-Azabu





Case 2) Remote Operation Demonstration in Japan t/w MLIT



- Objective: Demonstrate Remote Operation Concept
- Target ship: Tug boat "Yoshino Maru" (Shin-Nippon Kaiyosha)
- Project period: 2018.4 2021.3
- Project members: company name (role)
 - 1. MTI (project coordinator/concept design)
 - 2. JMS (project coordinator/simulator)
 - 3. NYK (project coordinator/ship owner)
 - 4. IKOUS (ship owner)
 - 5. Furuno Electric (navigation equipment)
 - 6. Japan Radio (navigation equipment)
 - 7. Tokyo Keiki (navigation equipment)
 - 8. BEMAC (DPS)
 - 9. Keihin Dock (shipyard)
 - 10. Mitsubishi Shipbuilding (engineering)
 - 11. Sky Perfect JSAT (satellite communication)
 - 12. NTT DoCoMo (4G/5G network)
 - 13. NTT (system provider)
 - 14. Niigata Power Systems(propulsion)
 - 15. ClassNK (verifier)
 - 16. NMRI (risk assessment)

Open Innovation by Diverse Expertise + Shared Concept + Project Management

Objective: Demonstration of the developed technology in i-Shipping (operation) project (2016-2020) and feedback to MLIT for their guideline & rule making





Autonomous Ship Framework

- APExS (Action Planning and Execution System)

 1^{st} demonstration was conducted on 22^{nd} January 2020. 2^{nd} demonstration will be conducted on 3^{rd} December 2020.

Remotely operate tug-boat in Tokyo bay from ROC in Nishinomiya (500km away)

Enhanced situation awareness

- Visualize collision risk











- Objective
 - Demonstrate functions for full autonomous ship
- Project consortium & partners
 - Consortium: 27 organizations (domestic)
 - Partners: 20 organizations (global)
- Target schedule
 - Demonstration in Feb 2022 (plan)





NYK GROUP



Operation Concept (ConOps), Risk Assessment, Model-based Systems Engineering (MBSE), System Reliability Test by using Simulation and Project Management → Development of Open Architecture & Open Process for Open Innovation for future complex system development & operation



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